## Hydrodynamics and Elasticity - Problem Sheet 8

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## Problem 4

We will prove the following identity:

$$F_x - iF_y = \frac{i\rho}{2} \oint \left(\frac{\mathrm{d}w}{\mathrm{d}z}\right)^2 \mathrm{d}z$$

The complex potential w is defined as  $w = \phi + i\psi$ , and it's differential is  $dw = d\phi + id\psi$ . At the body boundary, the velocity must be tangent to the surface, this means that the contour C is a streamline of the flow. The stream function  $\psi$  is constant along streamlines, so on C we have  $d\psi = 0$ . This allows us to write  $dw = d\phi = d\overline{w}$ . Using this fact we can transform the contour integral:

$$\oint_C \left(\frac{\mathrm{d}w}{\mathrm{d}z}\right)^2 \mathrm{d}z = \oint_C \frac{\mathrm{d}w}{\mathrm{d}z} \frac{\mathrm{d}w}{\mathrm{d}z} \frac{\mathrm{d}\overline{z}}{\mathrm{d}\overline{z}} \mathrm{d}z = \oint_C \frac{\mathrm{d}w}{\mathrm{d}z} \frac{\mathrm{d}\overline{w}}{\mathrm{d}z} \frac{\mathrm{d}\overline{z}}{\mathrm{d}\overline{z}} \mathrm{d}z = \oint_C \frac{\mathrm{d}w}{\mathrm{d}z} \frac{\mathrm{d}\overline{w}}{\mathrm{d}\overline{z}} \mathrm{d}\overline{z} = \oint_C \left|\frac{\mathrm{d}w}{\mathrm{d}z}\right|^2 \mathrm{d}\overline{z} = \oint_C v^2 \mathrm{d}\overline{z} = \oint_C v^2 (\mathrm{d}x - i\mathrm{d}y)$$

For steady, incompressible fluid we can use the Bernoulli's law:

$$\frac{p}{\rho} + \frac{v^2}{2} = c = \text{const} \implies v^2 = c - \frac{2p}{\rho}$$

Integrating the constant c over a closed contour will give a zero contribution, we will only consider the term with p.

$$\frac{i\rho}{2}\oint \left(\frac{\mathrm{d}w}{\mathrm{d}z}\right)^2\mathrm{d}z = -\frac{i\rho}{2}\cdot\frac{2}{\rho}\oint_C p\left(\mathrm{d}x-i\mathrm{d}y\right) = -\oint_C p\left(\mathrm{d}y+i\mathrm{d}x\right) = -\oint_C p\mathrm{d}y - i\oint_C p\mathrm{d}x = F_x - iF_y \quad \Box$$

Where we have used the fact that force in x direction is the integral of pressure over y "surface",  $-\oint_C pdy$ , and y force is the same for x surface,  $\oint_C pdx$ . The signs of the integrals is dependent on the contour orientation. Here we choose the standard anti-clockwise direction to get a minus sign in x and plus in y to obtain the form of the formula from the theorem.